Joseph Colonna

Professor Eckert

Sprint 3 tables

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **#** | **Requirement** | **Comments** | **Priority** | **Date Reviewed** | **SME Reviewed/ Approved** |
| E1 | Robot must avoid 3 obstacles. | Extra points added for every obstacle avoided/completed | 1 | 11/19/20 | We do not have a SME (Systems Management Expert) besides Professor Eckert. |
| E2 | Robot will go over a ramp. | Must do | 1 | 11/19/20 |  |
| E3 | Robot will roll into as many pins as possible. | Extra points added for ever pin knocked down | 1 | 11/19/20 |  |
| E4 |  |  |  |  |  |
| E5 |  |  |  |  |  |

|  |  |  |  |
| --- | --- | --- | --- |
| **Name** | **Role** | **Responsibility** | **Reports To** |
| Joseph Colonna | Algorithm  Tables | Writes the algorithm and most tables | Each other |
| John Costa | GitHub Manager  Editor  System Design Documentation | Manages collaborative GitHub account, edits all materials, writes System Design Document | Each other |
| Nicole Czerepak | Coder  Tester  Robot Owner | Writes block code, owner of the robot, tests code on robot and documents results, records sensor data graph | Each other |